

PHASE NOISE COMPENSATION FOR SPECTRAL MEASUREMENTS

Background of the Invention

The performance of spectrum analyzers can be degraded by phase noise that is
5 inherent within the spectrum analyzers. For example, phase noise can reduce
measurement accuracy of a spectrum analyzer when the phase noise of the spectrum
analyzer can not be isolated from signal measurements that are performed by the spectrum
analyzer. Phase noise can also limit measurement sensitivity of the spectrum analyzer. If
the phase noise of the spectrum analyzer is sufficiently high relative to the signals being
10 measured, the signals can be masked by the phase noise and go undetected by the
spectrum analyzer. Unfortunately, decreasing the phase noise of the spectrum analyzer to
improve the measurement accuracy and measurement sensitivity can be costly or difficult
to achieve, due to inherent noise within local oscillators, frequency references and other
components of the spectrum analyzers that contribute to phase noise. Accordingly, there is
15 motivation to compensate for the effects of phase noise on the measurements acquired by
spectrum analyzers.

One phase noise compensation technique is used in the Option 226 *Phase Noise
Measurement Personality* for the AGILENT TECHNOLOGIES, INC. model E4440A
PSA series Spectrum Analyzer. This technique includes characterizing the phase noise of
20 the spectrum analyzer by stimulating the spectrum analyzer with a signal having phase
noise that is substantially lower than that of the spectrum analyzer, and then measuring the
stimulus signal. The resultant phase noise from the measured stimulus signal is subtracted
on a linear power scale from subsequent signal measurements that are performed by the
spectrum analyzer. This phase noise characterization pertains only to the one particular
25 operating state of the spectrum analyzer at which the stimulus signal is measured.

Therefore, in order to compensate for phase noise using this technique, the characterization is typically performed upon each change of the operating state of the spectrum analyzer, which increases measurement set-up time for the spectrum analyzer.

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Summary of the Invention

A system and method according to embodiments of the present invention compensate for phase noise of a spectrum analyzer based on an established model of the phase noise that accommodates a variety of operating states of the spectrum analyzer. The model is used to form an array that is applied to extract an output signal from measurement
10 traces that are acquired by the spectrum analyzer.

Brief Description of the Drawings

Figures 1A-1F show exemplary signals relevant to spectral measurements by a spectrum analyzer.

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Figure 2 shows a block diagram of a phase noise compensation system according to embodiments of the present invention.

Figure 3 shows a block diagram of a measurement acquisition unit of a conventional spectrum analyzer.

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Figure 4 shows a flow diagram for establishing a phase noise model according to embodiments of the present invention.

Figures 5A-5B show exemplary signals relevant to the embodiments of the present invention.

Figure 6 shows a flow diagram of a phase noise compensation method according to alternative embodiments of the present invention.

Detailed Description of the Embodiments

Figures 1A-1F show exemplary signals relevant to spectral measurements acquired by a typical spectrum analyzer. Figure 1A shows a low noise continuous wave signal S_{CW} , at a frequency f_{CW} . Figure 1B shows a measured signal S_{Cwm} that results when the low noise continuous wave signal S_{CW} is measured by a spectrum analyzer. The spectrum analyzer has a phase noise φ_{SA} in the operating state at which the continuous wave signal S_{CW} is measured. The measured signal S_{Cwm} includes the phase noise φ_{SA} contributed by the spectrum analyzer and can be expressed as $S_{Cwm} = S_{CW} + S_{CW} * \varphi_{SA}$, where * indicates convolution. Thus, the measured signal S_{Cwm} can be expressed as the low noise continuous wave signal S_{CW} signal plus the low noise continuous wave signal S_{CW} convolved with the phase noise φ_{SA} of the spectrum analyzer.

Figure 1C shows a low-noise two-tone signal S_2 at frequencies f_1 and f_2 . Figure 1D shows a measured signal S_{2m} that results when the low-noise two-tone signal S_2 is measured by the spectrum analyzer. The measured signal S_{2m} includes phase noise φ_{SA} contributed by the spectrum analyzer and can be expressed as $S_{2m} = S_2 + S_2 * \varphi_{SA}$. Figure 1E shows a noisy signal S_N having a signal bandwidth N . Figure 1F shows a measured signal S_{Nm} that results when the noisy signal S_N is measured by the spectrum analyzer. The measured signal S_{Nm} includes phase noise φ_{SA} contributed by the spectrum analyzer and can be expressed as $S_{Nm} = S_N + S_N * \varphi_{SA}$.

In each instance, the phase noise φ_{SA} of the spectrum analyzer influences the measurements of signals that are applied to the spectrum analyzer. When a signal S_{IN} is applied to a typical spectrum analyzer, a measurement trace S_{MEAS} acquired by the

spectrum analyzer can be expressed as the applied signal S_{IN} plus the applied signal S_{IN} convolved with the phase noise φ_{SA} of the spectrum analyzer, as indicated in equation 1.

$$S_{MEAS} = S_{IN} + S_{IN} * \varphi_{SA} \quad (1)$$

Figure 2 shows a conventional spectrum analyzer 10, including a phase noise compensation system 12 in accordance with the embodiments of the present invention. The spectrum analyzer 10 includes a controller 14, typically a computer or other type of processor, that is coupled to a keyboard, touch screen, or other type of user interface 16. The user interface 16 can also be a computer that is coupled to the spectrum analyzer 10 via an interface bus or other communication path 15.

The user interface 16 provides an input 17, to the controller 14, which is used to adjust the operating state of the spectrum analyzer 10. The operating state includes the center frequency CF, the frequency span SPAN, and resolution bandwidth RBW settings for a measurement acquisition unit 18 of the spectrum analyzer 10. However, there may be additional operating states, or operating states that are different from these exemplary operating states, depending on the measurement acquisition unit 18 of the spectrum analyzer 10. The measurement acquisition unit 18 includes the components, elements or subsystems used to characterize the spectral content of signals S_{IN} that are applied to the spectrum analyzer 10. Figure 3 shows a simplified block diagram of the measurement acquisition unit 18 of a conventional spectrum analyzer 10, such as an AGILENT TECHNOLOGIES, INC. model E4440 PSA series Spectrum Analyzer, that includes an offset synthesizer SYNTH. The offset synthesizer SYNTH provides a local oscillator signal S_{LO} that establishes the center frequency CF and frequency span SPAN for the measurements performed by the spectrum analyzer 10. A filter 26 establishes the

resolution bandwidth RBW for the measurements performed by the spectrum analyzer 10.

The operation of a conventional spectrum analyzer is described, for example, in *Spectrum Analysis Basics*, Application Note 150, provided by AGILENT TECHNOLOGIES, INC., Palo Alto, California, USA.

5 The operating states of the spectrum analyzer 10 are set according to parameters within a designated parameter set 13 associated with the spectrum analyzer 10. The parameters are adjusted, set or otherwise designated via the controller 14 in response to the inputs provided by the user interface 16. An exemplary parameter set 13, tabulated in table 1, designates the operating states of a spectrum analyzer 10 that includes an offset
10 synthesizer SYNTH in the measurement acquisition unit 18.

Parameter	Parameter designation
Sampler IF frequency	f_{SIF}
Sampler IF polarity	P
Sampler harmonic number	N
PLL divide ratio	R

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The parameter settings that designate the operating states of the spectrum analyzer 10 also influence the phase noise φ_{SA} of the spectrum analyzer 10. For the parameter set
20 13 of table 1, the sampler IF frequency (intermediate frequency) f_{SIF} , sampler IF polarity P, sampler harmonic number N and PLL (phase lock loop) divide ratio R within the offset synthesizer SYNTH of the measurement acquisition unit 18 impact the phase noise φ_{SA} of the spectrum analyzer 10. Thus, when a signal S_{IN} is measured by the spectrum analyzer

10, the parameter settings that designate the operating state of the spectrum analyzer 10 for the measurement also establish the phase noise φ_{SA} that is contributed to the measurement by the spectrum analyzer 10.

The phase noise compensation system 12 shown in Figure 2 includes a computational unit 20 and a signal processor 22. While the computational unit 20 and the signal processor 22 are shown separate from the controller 14, the computational unit 20 and the signal processor 22 are typically implemented within the controller 14. The computational unit 20 forms an array C from a phase noise model $\mathcal{L}(f_{\text{OFFSET}})$ that represents the phase noise φ_{SA} of the spectrum analyzer 10 at frequency offsets f_{OFFSET} . The phase noise model $\mathcal{L}(f_{\text{OFFSET}})$ is based on the parameter settings that correspond to the operating state of the spectrum analyzer 10. The signal processor 22 applies the array C to measurements of the signal S_{IN} , acquired by the measurement acquisition system 18, to extract an output signal S_{OUT} . The output signal S_{OUT} is a representation of the signal S_{IN} that includes compensation to reduce the influence of the phase noise φ_{SA} of the spectrum analyzer 10.

Figure 4 shows a flow diagram 40 for establishing the phase noise model $\mathcal{L}(f_{\text{OFFSET}})$, which includes applying a series of calibration signals $S1_{\text{CAL}} \dots SN_{\text{CAL}}$ to the spectrum analyzer 10 (step 41). The calibration signals $S1_{\text{CAL}} \dots SN_{\text{CAL}}$ stimulate the spectrum analyzer 10 at a sufficient number of frequencies or other stimulus conditions to enable the phase noise φ_{SA} of the spectrum analyzer 10 to be represented at predetermined frequency offsets f_{OFFSET} and at the various parameter settings that designate the operating states of the spectrum analyzer 10.

In step 42 of the flow diagram 40, the parameters in the parameter set 13 are adjusted to settings $\{f_{\text{OFFSET}}, f_{\text{SIF}}, P, N, R\}_{\text{CAL}}$ that designate corresponding operating states of the spectrum analyzer for the measurement of each of the calibration signals $S1_{\text{CAL}} \dots SN_{\text{CAL}}$. Step 44 includes measuring each of the calibration signals $S1_{\text{CAL}} \dots SN_{\text{CAL}}$ at the center frequency CF, frequency span SPAN and resolution bandwidth RBW determined by the operating state designated by the settings $\{f_{\text{OFFSET}}, f_{\text{SIF}}, P, N, R\}_{\text{CAL}}$ of the parameters in the parameter set 13. The phase noise φ_{SA} of the spectrum analyzer 10 at predetermined frequency offsets f_{OFFSET} from the measured calibration signals is isolated in step 46 to form a phase noise calibration set $\varphi_{\text{CAL}}\{f_{\text{OFFSET}}, f_{\text{SIF}}, P, N, R\}_{\text{CAL}}$, which is a function of the parameters in the parameter set 13 adjusted to the settings $\{f_{\text{OFFSET}}, f_{\text{SIF}}, P, N, R\}_{\text{CAL}}$. The calibration signals $S1_{\text{CAL}} \dots SN_{\text{CAL}}$ applied to the spectrum analyzer have substantially lower phase noise than the spectrum analyzer 10, so that the phase noise of each measured calibration signal is attributed to the spectrum analyzer 10. Alternatively, the phase noise of the calibration signals $S1_{\text{CAL}} \dots SN_{\text{CAL}}$ has low uncertainty, so that the phase noise φ_{SA} of the spectrum analyzer 10 can be isolated by subtracting, on a linear power scale, the phase noise of the calibration signals from the total phase noise that is measured by the spectrum analyzer, where this subtraction is performed at the frequency offsets f_{OFFSET} .

Step 48 includes establishing the phase noise model $\mathcal{L}(f_{\text{OFFSET}})$ as a set of functions F of the frequency offsets f_{OFFSET} and the parameters in the parameter set 13. When the parameter set includes the exemplary parameters of table 1, the phase noise model is expressed as $\mathcal{L}(f_{\text{OFFSET}}) = F\{f_{\text{OFFSET}}, f_{\text{SIF}}, P, N, R\}$. The functions F include a series of contours, typically represented by coefficients, polynomial terms, or elements in an array

or look-up table, which result from curve fitting or other mappings of phase noise at frequency offsets f_{OFFSET} to the phase noise calibration set $\varphi_{\text{CAL}}\{f_{\text{OFFSET}}, f_{\text{SIF}}, P, N, R\}_{\text{CAL}}$ established in step 46.

In one example, the set of functions F are linear, wherein each function F_x within
 5 the set of functions F has a slope m that is a function of the sampler IF polarity P , the
 sampler harmonic number N and the PLL divide ratio R . Each function F_x also has an
 offset b that is a function of the sampler IF polarity P , the sampler harmonic number N and
 PLL divide ratio R . The linear relationship for the modeled phase noise of the spectrum
 analyzer 10 and sampler IF frequency f_{SIF} for each setting or adjustment of the sampler IF
 10 polarity P , the sampler harmonic number N and the PLL divide ratio R , at the offset
 frequency f_{OFFSET} , is expressed as $\mathcal{L}(f_{\text{OFFSET}}) = m\{f_{\text{OFFSET}}, P, N, R\} f_{\text{SIF}} + b\{f_{\text{OFFSET}}, P, N,$
 $R\}$

The phase noise model $\mathcal{L}(f_{\text{OFFSET}})$ provides a mapping or correspondence between
 phase noise φ_{SA} of the spectrum analyzer 10 at frequency offsets f_{OFFSET} , and settings of
 15 the parameters in the parameter set 13. Thus, for a given operating state of the spectrum
 analyzer 10 that is designated by the parameters, the phase noise φ_{SA} of the spectrum
 analyzer 10 can be determined from the phase noise model $\mathcal{L}(f_{\text{OFFSET}})$. Typically, the
 phase noise model $\mathcal{L}(f_{\text{OFFSET}})$ is stored in a memory or other storage medium (not shown)
 that is accessible to the controller 14.

20 Once the phase noise model $\mathcal{L}(f_{\text{OFFSET}})$ is established, applied signals are
 subsequently measured by the spectrum analyzer 10. For example, the measurement
 acquisition unit 18 receives the signal S_{IN} and acquires a measurement trace S_{MEAS} that

represents the signal S_{IN} . The measurement trace S_{MEAS} , typically stored in a display memory 24, is acquired at an operating state that includes a designated setting of the center frequency CF, frequency span SPAN, and resolution bandwidth RBW. The measurement trace S_{MEAS} has a predetermined number of measurement points n , designated by an integer index i , as shown in Figure 5A.

The computational unit 20 forms the array C from the phase noise model $\mathcal{L}(f_{OFFSET})$, based on the frequency span SPAN and the number of measurement points n in the measurement trace S_{MEAS} . Typically, the array C is designated to have $2n+1$ points, as shown in Figure 5B. Each point in the array C, designated by the index i , has a corresponding value C_i , established from the phase noise model $\mathcal{L}(f_{OFFSET})$ evaluated at offset frequencies $f_{OFFSET} = |i| \text{ SPAN}/(n-1)$. The array C comprises a set of values C_i that are power ratios expressed on a linear scale. For an array C having $2n+1$ points, the indices i of the values C_i are integers that vary from $-n$ to n .

In one example, the values C_i of the array C at each index i is established according to equation 2.

$$C_i = \text{NBW} 10^{0.1 \mathcal{L}(\text{SPAN}(|i|)/(n-1))} \quad (2)$$

In equation 2, the term NBW represents the noise bandwidth of the spectrum analyzer 10, established based on the setting of the resolution bandwidth RBW of the spectrum analyzer 10. The noise bandwidth NBW is typically a designated multiple of the resolution bandwidth RBW.

The signal processor 22 applies the array C to the measurement trace S_{MEAS} to extract the output signal S_{OUT} . Applying the array C typically includes a numerical convolution of the measurement trace S_{MEAS} with the array C and a subtraction of the

resulting convolution $S_{MEAS} * C$ from the measurement trace S_{MEAS} . The measurement trace S_{MEAS} and the array C are each expressed on a linear power scale for this processing by the signal processor 22. While the resulting convolution $S_{MEAS} * C$ has $3n+1$ points when the measurement trace S_{MEAS} has n points and the array C has $2n+1$ points, the middle n points of the resulting convolution $S_{MEAS} * C$ are used in the subtraction of the resulting convolution $S_{MEAS} * C$ from the n measurement points in the measurement trace S_{MEAS} .

The output signal S_{OUT} provided by the signal processor 22 as a result of applying the array C to the measurement trace S_{MEAS} is expressed in equation 3.

$$S_{OUT} = S_{MEAS} - S_{MEAS} * C \quad (3)$$

Due to the influence of the phase noise φ_{SA} of the spectrum analyzer 10 on the measurements acquired by the spectrum analyzer 10, an expression for the output signal S_{OUT} results in equation 4, where the term S_{INm} depicts the signal S_{IN} at the n measurement points.

$$S_{OUT} = S_{INm} + S_{INm} * \varphi_{SA} - S_{INm} * C - S_{INm} * \varphi_{SA} * C \quad (4)$$

Since the array C provides an estimate of the phase noise φ_{SA} of the spectrum analyzer 10, the array C is approximately equal to the phase noise φ_{SA} of the spectrum analyzer 10, causing the output signal S_{OUT} to be approximately equal to $S_{INm} - S_{INm} * \varphi_{SA} * C$. Because the phase noise φ_{SA} of the spectrum analyzer 10 and the array C have low values when expressed on linear power scales, the term $S_{INm} * \varphi_{SA} * C$ in the expression for S_{OUT} is negligible relative to the term S_{INm} . Thus, the resulting output signal

S_{OUT} is approximately equal to S_{INm} , and is a representation of the signal S_{IN} that includes compensation to reduce the influence of the phase noise φ_{SA} of the spectrum analyzer 10.

Figure 6 shows a flow diagram of a phase noise compensation method 50 according to alternative embodiments of the present invention. Step 52 includes
 5 establishing the phase noise model for the spectrum analyzer. This step in the phase noise compensation method 50 typically includes applying the series of calibration signals $S1_{CAL}...SN_{CAL}$ to the spectrum analyzer 10, and adjusting the parameters in the parameter set 13 to the settings $\{f_{OFFSET}, f_{SIF}, P, N, R\}_{CAL}$ to designate corresponding operating states of the spectrum analyzer for the measurement of each of the calibration signals
 10 $S1_{CAL}...SN_{CAL}$. Each of the calibration signals $S1_{CAL}...SN_{CAL}$ is then measured at the center frequency CF, frequency span SPAN and resolution bandwidth RBW determined by the designated operating state. Then, the phase noise φ_{SA} of the spectrum analyzer 10 is isolated at predetermined frequency offsets f_{OFFSET} from the measured calibration signal to form the phase noise calibration set $\varphi_{CAL}\{f_{OFFSET}, f_{SIF}, P, N, R\}_{CAL}$, when the parameter
 15 set 13 includes the parameters of table 1. Then, the phase noise model $\mathcal{L}(f_{OFFSET})$ is established as the set of functions F , of the frequency offsets f_{OFFSET} and the parameters in the parameter set 13.

In step 54, one or more measurement traces S_{MEAS} are acquired by the measurement acquisition unit 18 of the spectrum analyzer in response to the signal S_{IN}
 20 applied to the spectrum analyzer 10.

In step 56, the array C is formed from the phase noise model, based on the operating state of the spectrum analyzer 10 designated by the parameter set 13, including, for example, the frequency span SPAN, and the number of measurement points n in the

measurement trace S_{MEAS} . While step 54 is shown proceeding step 56, the array C can be formed before or after the acquisition of measurement traces S_{MEAS} .

Step 58 includes applying the array C to the measurement trace S_{MEAS} to extract the output signal S_{OUT} . This typically includes a numerical convolution of the
5 measurement trace S_{MEAS} with the array C and then a subtraction of the resulting convolution $S_{MEAS} * C$ from the measurement trace S_{MEAS} , where the measurement trace S_{MEAS} and the array C are each expressed on a linear power scale.

While the embodiments of the present invention have been illustrated in detail, it should be apparent that modifications and adaptations to these embodiments may occur to
10 one skilled in the art without departing from the scope of the present invention as set forth in the following claims.